

## Bullet Physics User Manual

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## Introduction

Bullet Physics is an open source collision detection and physics library, related tools, demos, applications and a forum. It is created as a skunk project by Erwin Coumans, ex-Havok employee, free for commercial use. Primary location of the software and the forum is <http://www.continuousphysics.com/Bullet/phpBB2/index.php>.

Target audience for this work are physics enthusiasts who want to play with collision detection and rigidbody dynamics concepts. Furthermore it can be used by end users in 3D animation and gaming as part of Blender integration (<http://www.blender.org>). Intention is also to provide a sample integration with Collada Physics importer, which can load physics worlds exported by most 3D authoring packages. See <http://www.collada.org> for more details.

## Quickstart

For end users who want to experiment with Blender should refer to section Blender Bullet Integration. There is a step by step introduction to create and simulate worlds using Bullet. It is recommended to see the provided demos first. This gives an idea of the concepts in this manual.

If you want to use Bullet in your own 3D application, it is best to follow the steps in the CcdPhysicsDemo. In a nutshell:

Create a CcdPhysicsEnvironment object. For each RigidBody, create a CcdPhysicsController, and add this to the CcdPhysicsEnvironment. Then every frame, you need to update the CcdPhysicsEnvironment by calling the Proceed method, passing the elapsed time.

To construct a CcdPhysicsController, you need to provide:

- a CollisionShape, like a Box, Sphere, Cone, Convex Hull or Triangle Mesh
- Mass and Material properties like friction and restitution
- a link to your Graphics object by deriving from MotionState

Bullet will update the position of every Graphics Objects, by simulating the Rigidbodies, performing Collision Detection, and synchronizing the transform by calling your provided MotionState. There is performance functionality like auto deactivation for non moving objects, and debugging feedback that can be linked to your renderer. See Debugging section for this.

## **Demos**

### ***OpenGL***

sample text

### ***CcdPhysicsDemo***

sample text

### ***Raytracer***

sample text

### ***GjkConvexCastDemo***

sample text

### ***ConvexHullDistance***

sample text

### ***ConcaveDemo***

sample text

### ***CollisionDemo***

sample text

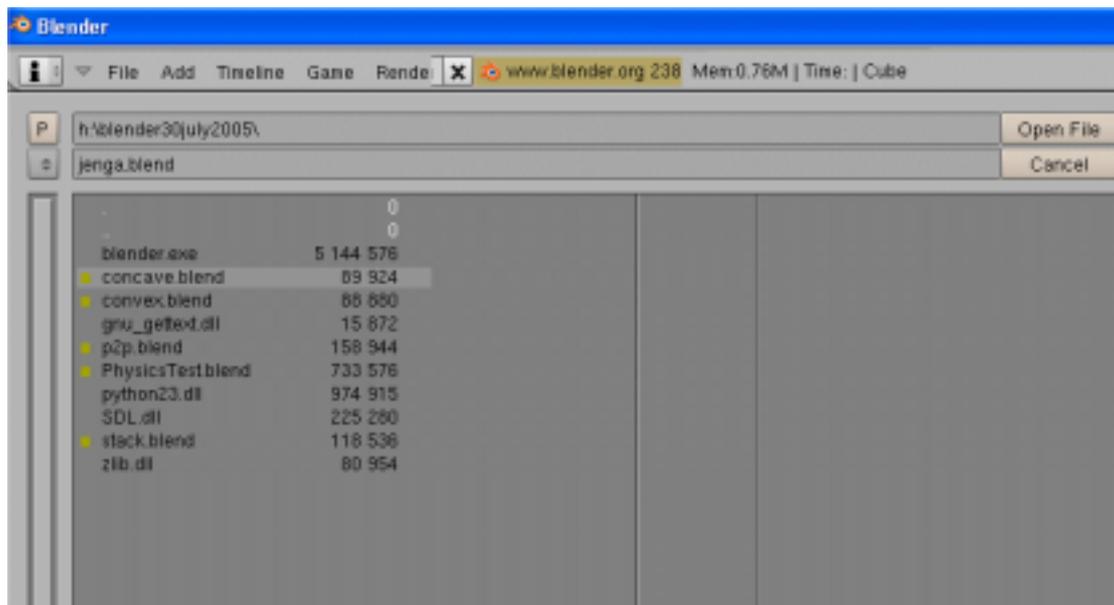
### ***SimplexDemo***

sample text

## Blender Bullet Integration

Download Blender 2.38 or later, for Windows, Linux or other platforms from <http://www.blender.org>. A preview can be downloaded in the Blender section of the Bullet forum at <http://www.continuousphysics.com/Bullet/phpBB2/index.php>.

There are some ready made Blender demos that are ready to play. Get them at the Bullet Forum, in the Blender section. Start Blender, and make sure the mouse pointer is in the middle of the 3D window. Then select menubar File/Open or press F1 to open a file:



Left click a file, or use the slider and left click a foldername or .. to navigate, and folder. Then make sure the filename is shown, and left click Open File button, or middleclick on the filename. Another quick option is, instead of pressing F1, press <CTRL>+O, to open the last saved file. Blender remembers this even when you quit the program.

When the file is loaded in Blender, you can play the simulation by moving the mouse cursor in the 3D view, and press 'P'. Alternatively use menu Game/Start Game. To stop the playback you can press <ESCAPE>.



Todo: Show how to bake keyframes for blender animation. For now there is a script called Game2Ipo, which can be found in <http://www.elysiun.com> It is not compatible with the Bullet Blender build yet. Watch the Bullet Forum for news on this. Other option will be a better physics - animation integration which is done for ODE, as a Google Summer Project. Bullet and ODE will be supported: <http://wiki.blender.org/bin/view.pl/Blenderdev/OdePhysicsIntegration>.

## Collada Physics Importer

Todo:

ColladaMaya exporter

<http://colladamaya.sourceforge.net/>

Collada Physics Schema

Collada Importer / Viewer

## Bullet SDK Collision Detection and Physics Basics

### ***Latest Bullet Version from CVS:***

```
cvs -z3 -d:pserver:anonymouse@cvs.blender.org:/cvsroot/bf-blender co  
blender/extern/bullet
```

Download zipped sources of Bullet and the demos in Bullet Forum “[Bullet Continuous Collision Detection and Physics Library](http://www.continuousphysics.com/Bullet/phpBB2/index.php)” in <http://www.continuousphysics.com/Bullet/phpBB2/index.php>

### ***Browse Bullet On-line:***

<http://projects.blender.org/viewcvs/viewcvs.cgi/blender/extern/bullet/?cvsroot=bf-blender>

### **Bullet Doxygen Documentation** On-line

<http://www.continuousphysics.com/Bullet/BulletFull/html/annotated.html>

Please note this is not always up to date, it has to be uploaded manually.

It is best to generate the documentation from the sources: Download doxygen, and run ‘doxygen’ in the Bullet folder. There is a Doxyfile provided, which recursively traverses all sources. For best result also install graphviz for the graphical class diagram and graphical collaboration diagram.

Todo:

### ***CollisionShapes***

Box, Sphere, Cylinder, Minkowski Sum, Convex Hull, (Concave) Triangle Mesh, TriangleMeshInterface

### ***BroadphaseCollision***

Axis Aligned Bounding Box optimization to prevent expensive calculations between every pair of Rigidbodies.

Simple Broadphase

## ***NarrowPhaseCollision***

**GetClosestPoint** query, GJK

**Raycast**,

**Convex Cast** (sweep),

**GetTimeOfImpact** (linear + angular motion)

## **CollisionDispatch**

todo: find the appropriate collision detection algorithm for a pair of CollisionShapes

## **Dynamics**

## **ConstraintSolver**

## **Debugging**

### ***IDebugDraw***

todo:

Explain usage of the IDebugDraw interface. See the CcdPhysicsDemo which implements a callback. Also Blender has a callback for in-game debugging.